

Πανελλαδικές εξετάσεις 2021

Φυσική 22/6/2021

Απαντήσεις θεμάτων

Θέμα Α

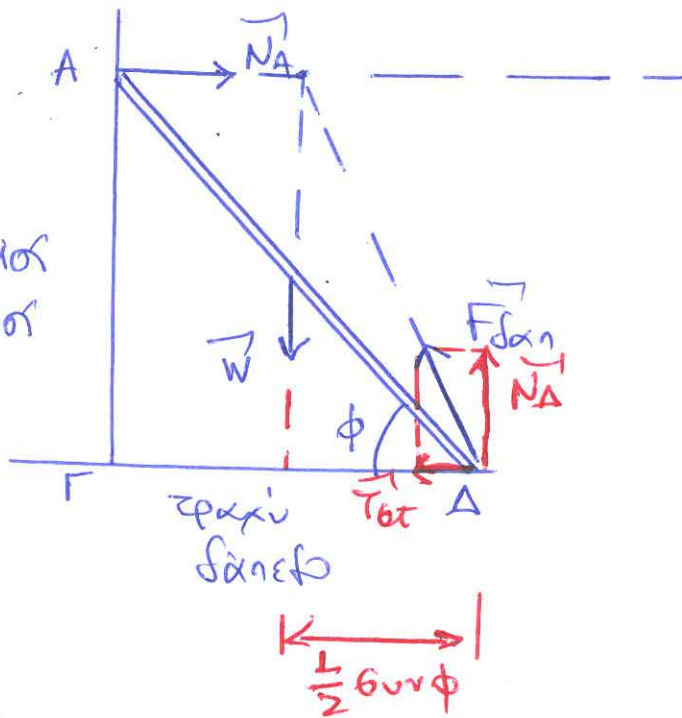
A1 δ A2 δ A3 δ A4 β
A5 α Σ β Λ γ Σ δ Σ ε Λ

Θέμα Β

B1 α) (ii)

$\mu \rightarrow \mu_{\text{σορ}}$

$L \sin \phi$ λείος
 $L \cos \phi$ ζείχος



Η βρύση ισορροπεί:

$$\sum \vec{\tau}(A) = \vec{0} \quad \text{ή} \quad \sum \tau(A) = 0 \quad N_{\Delta} \tau_{NA(A)} + \tau_W(A) + \tau_{F_{\Delta x}}(A) = 0$$

$$\text{ή} \quad -N_{\Delta} \cdot L \sin \phi + W \cdot \frac{L}{2} \cos \phi = 0 \quad \text{ή} \quad N_{\Delta} \sin \phi = \frac{W}{2} \cos \phi$$

$$\text{ή} \quad N_{\Delta} = \frac{W \cos \phi}{2 \sin \phi}$$

$$\sum \vec{F} = \vec{0} \quad \text{ή} \quad \begin{cases} \sum F_x = 0 \\ \sum F_y = 0 \end{cases} \quad \left\{ \begin{array}{l} |N_{\Delta}| = |T_{\Delta x}| = \frac{W \cos \phi}{2 \sin \phi} \\ |N_{\Delta}| = |\vec{W}| = W \end{array} \right.$$

$$\text{απει} \quad T_{\text{ext}} \leq T_{\text{otmax}} \Rightarrow \frac{w}{2} \frac{\text{buv}\phi}{\eta\phi} \leq \mu_s \cdot N_A \Rightarrow$$

$$\Rightarrow \frac{w}{2} \frac{\text{buv}\phi}{\eta\phi} \leq \mu_s \cdot w \Rightarrow \mu_s \geq \frac{1}{2} \frac{\text{buv}\phi}{\eta\phi}$$

$$\text{αρα} \quad \mu_{\text{σφιανός}} = \mu = \frac{1}{2} \frac{\text{buv}\phi}{\eta\phi} \Rightarrow \frac{\eta\phi}{\text{buv}\phi} = \frac{1}{2\mu} \Rightarrow$$

$$\Rightarrow \boxed{\epsilon\phi\phi = \frac{1}{2\mu}}$$

B2 α) (L)

$$\beta) \text{ έμβολο ισορροπεί} \quad \Sigma \vec{F} = \vec{0} \Rightarrow |\vec{F}_{\text{ατμ}}| + |\vec{w}| = |\vec{F}_{\text{υδρ}}|$$

$$\Rightarrow P_{\text{ατμ}} A + w = P_{\text{υδρ}} \cdot A \quad (1) \quad (P_{\text{υδρ}}, P_1 = P_{\text{υδρ}} + \rho g h)$$

$$\text{εξ. συνέχειας } 1, 2 \quad A v_1 = \frac{A}{2} v_2 \Rightarrow v_1 = \frac{v_2}{2}$$

$$\text{εξ. Bernoulli} \quad \text{εξ. επιφάνεια } 2$$

$$\dots \Rightarrow P_{\text{ατμ}} + \rho g H + 0 = P_{\text{ατμ}} + \frac{1}{2} \rho v_2^2 + 0 \Rightarrow$$

$$\Rightarrow \frac{1}{2} \rho v_2^2 = \rho g H \Rightarrow v_2^2 = 2gH \Rightarrow |\vec{v}_2| = \sqrt{2gH} \quad (2)$$

$$\text{εξ. Bernoulli } 1, 2$$

$$P_1 + \frac{1}{2} \rho v_1^2 + 0 = P_{\text{ατμ}} + \frac{1}{2} \rho v_2^2 + 0 \Rightarrow$$

$$\Rightarrow P_{\text{υδρ}} + \rho g h + \frac{1}{2} \rho \frac{v_2^2}{4} = P_{\text{ατμ}} + \frac{1}{2} \rho v_2^2 \Rightarrow$$

$$\Rightarrow P_{\text{υδρ}} = P_{\text{ατμ}} + \frac{3}{8} \rho v_2^2 - \rho g h \quad (2)$$

$$\Rightarrow P_{\text{υδρ}} = P_{\text{ατμ}} + \frac{3}{4} \rho \cdot \cancel{2gH} - \rho g \frac{H}{4} \Rightarrow$$

$$\Rightarrow P_{\text{υδρ}} = P_{\text{ατμ}} + \frac{1}{2} \rho g H \quad \xrightarrow{(1A)}$$

$$\Rightarrow P_{\text{υδρ}} \cdot A = P_{\text{ατμ}} A + \frac{1}{2} \rho g H A \quad \xrightarrow{(1)}$$

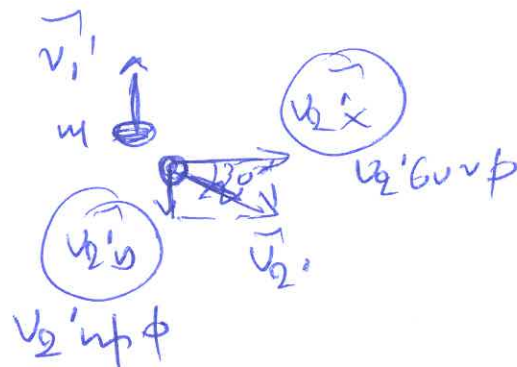
(2)

$$\Rightarrow P_{\cancel{A}} + W = P_{\cancel{A}} + \frac{1}{2} \epsilon g H A \Rightarrow$$

$$\Rightarrow \boxed{W = \frac{\epsilon g H A}{2}}$$

B3 (iii)

$$m \vec{v}_1 \quad 2m, \vec{v}_2 = \vec{0}$$



ελαστική πλάγια κρούση $m, 2m$

$$\text{ΑΔΟ} \quad \vec{p}_{\text{before}} = \vec{0} \Rightarrow p_{1x} = p_{2x} \quad \Rightarrow \left. \begin{aligned} p_{1x} &= p_{2x} \\ p_{1y} &= p_{2y} \end{aligned} \right\} \Rightarrow$$

$$\Rightarrow m|\vec{v}_1| = 2m|\vec{v}_2'| \cos 30^\circ \quad \left. \begin{aligned} 0 &= m|\vec{v}_1'| - 2m|\vec{v}_2'| \sin 30^\circ \end{aligned} \right\} \Rightarrow \left. \begin{aligned} |\vec{v}_1| &= 2 \frac{\sqrt{3}}{2} |\vec{v}_2'| \\ |\vec{v}_1'| &= 2 |\vec{v}_2'| \frac{1}{2} \end{aligned} \right\}$$

$$\Rightarrow |\vec{v}_1| = \sqrt{3} |\vec{v}_2'| \quad \leadsto \quad |\vec{v}_2'| = |\vec{v}_1'| = \frac{|\vec{v}_1|}{\sqrt{3}} = \frac{\sqrt{3}}{3} |\vec{v}_1|$$

$$|\vec{v}_1'| = |\vec{v}_2'|$$

(ii) όπως ΑΔΕ για κρούση ελαστική

$$\therefore \quad K_1 = K_1' + K_2' \Rightarrow \frac{1}{2} m v_1^2 = \frac{1}{2} m v_1'^2 + \frac{1}{2} \cdot 2m v_2'^2$$

$$\Rightarrow v_1^2 = v_1'^2 + 2v_2'^2 \quad \Rightarrow \quad v_1^2 = 3v_1'^2 \Rightarrow$$

$$\Rightarrow |\vec{v}_1'| = \frac{|\vec{v}_1|}{\sqrt{3}} = \frac{\sqrt{3}}{3} |\vec{v}_1|$$

πλ. κρούση $\Sigma_1, \Sigma_3 \quad \dots \quad \text{ΑΔΟ} \quad m v_1' = 2m v_K \Rightarrow$

$$\Rightarrow v_K = \frac{v_1'}{2}$$

$$\text{à pà} \quad \frac{k_{\text{oub}}}{k_1} = \frac{\frac{1}{2} \cdot 2\pi \cdot v_1^2}{\frac{1}{2} \pi \cdot v_1^2} = \frac{\cancel{2} \frac{v_1'^2}{4}}{v_1^2} = \frac{v_1'^2}{2v_1^2}$$

$$= \frac{\left(\frac{\sqrt{3}}{3} |\vec{v}_1|\right)^2}{2v_1^2} = \frac{\frac{1}{3} v_1^2}{2v_1^2} = \frac{1}{6} \Rightarrow \boxed{\frac{k_{\text{oub}}}{k_1} = \frac{1}{6}}$$

Θέμα Γ

$$l = 1\text{m} \quad m = 0,5\text{kg} \quad R_{\text{un}} = 2\Omega \quad v = v_{\text{th}}(\omega t) = v_{\text{th}}(50\pi t)$$

$$R_1 = 6\Omega \quad R_2 = 3\Omega$$

(Γ1) Si κλειστοί, δ_2, δ_3 ανοικτοί $\overline{P}_{R_1} = 12\text{W}$

$$(v_{R_1} = v) \quad \overline{P}_{R_1} = I_{\text{R}_1}^2 \cdot R_1 \Rightarrow I_{\text{R}_1} = \sqrt{\frac{P_{R_1}}{R_1}} = \sqrt{\frac{12}{6}} \text{ A} \Rightarrow$$

$$\Rightarrow I_{\text{R}_1} = \sqrt{2} \text{ A}, \quad I_{\text{R}_1} = \frac{I}{\sqrt{2}} \Rightarrow I = \sqrt{2} I_{\text{R}_1} = 2 \text{ A}$$

$$\text{και} \quad V = I \cdot R_1 = 12 \text{ Volt}$$

(Γ2) $f \rightarrow 2f$, $\omega \rightarrow 2\omega$ $50\pi \frac{r}{s} \rightarrow 100\pi \frac{r}{s}$

$$V = N\omega BA$$

$$V' = N\omega' BA = 2N\omega BA = 24 \text{ V}$$

$$\text{à pà} \quad v'(t) = 24 \sin(100\pi t) \quad \text{και} \quad i'(t) = \frac{v'(t)}{R_1} \Rightarrow$$

$$\Rightarrow i'(t) = 4 \sin(100\pi t), \text{ (SI)}$$

$$\text{οπότε} \quad p(t) = v'(t) \cdot i'(t) = 96 \sin^2(100\pi t), \text{ (SI)}$$

$$\text{για} \quad t_1 = 5 \cdot 10^{-3} \text{ s} \rightarrow p(t_1) = 96 \sin^2(100\pi \cdot 5 \cdot 10^{-3}) =$$

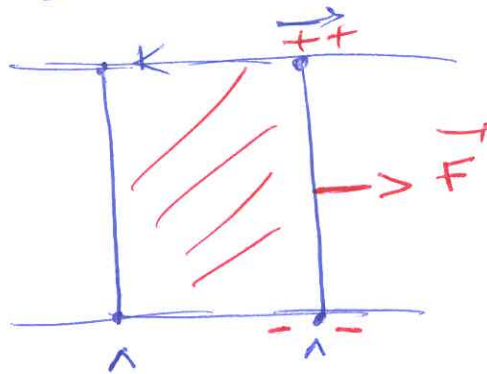
$$= 96 \sin^2\left(\frac{\pi}{2}\right) \stackrel{\text{cf 2)}}{=} 96 \cdot 1 \frac{\text{J}}{\text{s}} = 96 \text{ W}$$

(4)

Γ3, δ1 αραχτός $F=0, SN \rightarrow$

$t=2s$ δ2, δ3 κλειστά $v=at$

από $0 \rightarrow 2s$

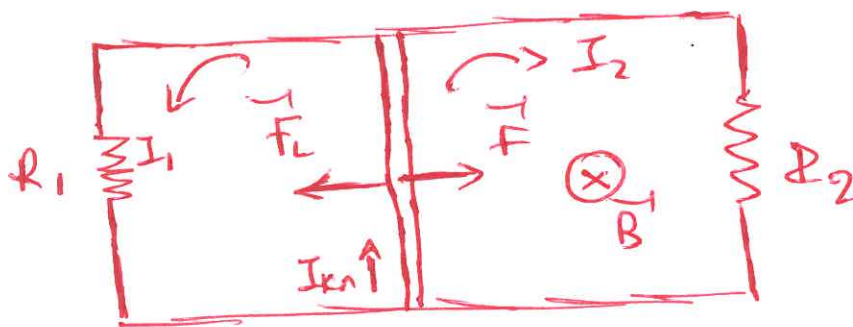


$$\mathcal{E}_{\text{em}} = -N \frac{d\phi}{dt} \Rightarrow |\mathcal{E}_{\text{em}}| = \left| \frac{d\phi}{dt} \right| = B \cdot l \frac{dx}{dt} = bvl$$

$$\Sigma \vec{F} = \vec{F} = m \cdot \vec{a} \Rightarrow |\vec{a}| = \frac{|\vec{F}|}{m} = 1 \text{ m/s}^2 \quad \text{Ε.Ο.Ε.Κ.}$$

$$v(2) = a \cdot t = 2 \frac{\text{m}}{\text{s}} \quad \rightarrow \quad \mathcal{E}_{\text{em}} = bvl$$

για $2s$, δ2, δ3 κλειστά



$$v=v_{\text{op}}, a=0 \text{ m/s}^2 \Rightarrow \Sigma \vec{F} = 0 \text{ N} \Rightarrow |\vec{F}| = |\vec{F}_2| \Rightarrow$$

$$\Rightarrow F = B \cdot I_{\text{cn}} l \quad (1)$$

$$\text{όπως } V_{R1} = V_{\text{cn}} = V_{R2} \Rightarrow I_1 R_1 = \mathcal{E}_{\text{em}} - I_{\text{cn}} R_{\text{cn}} = I_2 R_2$$

$$\text{και } I_{\text{cn}} = I_1 + I_2$$

$$\mu\epsilon \quad R_1 \parallel R_2 \Rightarrow R_{1,2} = \frac{R_1 R_2}{R_1 + R_2} = \frac{6 \cdot 3}{6 + 3} = \frac{18}{9} \Omega = 2\Omega$$

$$R_{\text{ολ}} = R_{1,2} + R_{\text{cn}} = 4\Omega$$

$$I_{\text{cn}} = I_{\text{ολ}} = \frac{bvl}{R_{\text{ολ}}} = \frac{23}{4} = \frac{B}{2} \quad (\text{SI})$$

(5)

$$\text{and } \textcircled{1} \Rightarrow F = B \cdot \frac{B}{2} l \Rightarrow B^2 = \frac{2F}{l} \Rightarrow$$

$$\Rightarrow |B| = \sqrt{\frac{1}{1}} \quad T = 1T.$$

$$\textcircled{r4} \Delta x_{0A} = \Delta x_{0 \rightarrow 2} + \Delta x_{2 \rightarrow 5} = \frac{1}{2} \underbrace{at^2}_{(0 \rightarrow 2)} + v_{op} \cdot (5-2) =$$

$$= \frac{1}{2} 1 \cdot 4 + 2 \cdot 3 \stackrel{(12)}{=} 8m$$

$$\text{also } W_F = F \cdot \Delta x_{0A} = 4J$$

$$Q_{R2} = I_2^2 \cdot R_2 \cdot \Delta t \quad (\Delta t = 5-2 = 3s)$$

$$I_2 = \frac{\mathcal{E}_{em} = I_1 R_1}{R_2} = \frac{Bvl - \frac{B}{2} \cdot l \cdot v}{R_2} = \frac{2 - \frac{1}{2} \cdot 2}{3} A$$

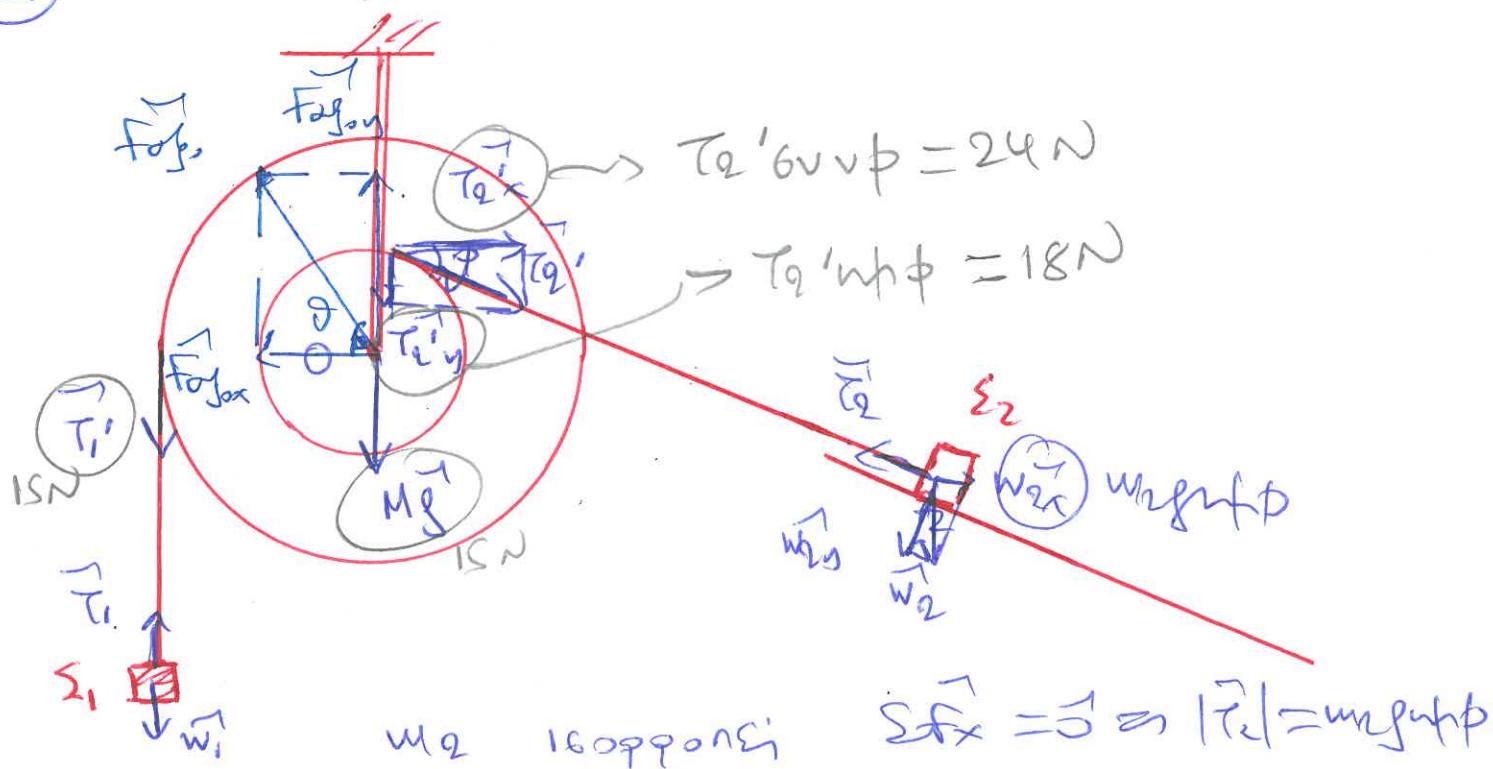
$$\Rightarrow \boxed{I_2 = \frac{1}{3} A} \quad \text{and TE} \quad Q_{R2} = \frac{1}{9} \cdot 3 \cdot 3 J = 1J$$

$$\text{Συνηώως } \eta\% = \frac{Q_{R2}}{W_F} 100\% = \frac{1}{4} 100\% = 25\%$$

Θέμα Δ

$M = 1,5 \text{ kg}$ $r, 2r$ $m_2 = 5 \text{ kg}$ λείο κεκλιμένο
 $\psi\phi = 0,6$ $\sigma\nu\phi = 0,8$ $m_3 = 5 \text{ kg}$, k , $d = 0,2 \text{ m}$
 βυθισμένη

Δ1



$$\Rightarrow |\vec{T}_2| = 50 \cdot 0,6 \text{ N} = 30 \text{ N}$$

$$\text{ροοξγία } \Sigma \vec{r}(o) = \vec{0} \Rightarrow \dots \Rightarrow +T_1' \cdot 2r - T_2' \cdot r = 0 \Rightarrow$$

$$\Rightarrow T_1' \cdot 2r = T_2' \cdot r \Rightarrow T_1' = \frac{T_2'}{2} = 15 \text{ N}$$

$$\text{αβ-φιν νήματα } |\vec{T}_1'| = |\vec{T}_1| = 15 \text{ N}$$

$$|\vec{T}_2| = |\vec{T}_2'| = 30 \text{ N}$$

$$m_1 \text{ ισορροπεί } \Sigma \vec{F} = \vec{0} \Rightarrow |\vec{w}_1| = |\vec{T}_1| \Rightarrow m_1 g = |\vec{T}_1|$$

$$\Rightarrow m_1 = \frac{|\vec{T}_1|}{g} = 1,5 \text{ kg} \Rightarrow \boxed{m_1 = 1,5 \text{ kg}}$$

7

Σροχυσία ισορροπεί

$$\left. \begin{aligned} \sum \vec{F} = \vec{0} \Rightarrow \sum F_x = 0 \\ \sum F_y = 0 \end{aligned} \right\} \Rightarrow \begin{aligned} |F_{T2x}| &= |\vec{T}_2'| = T_2' \sin \theta = 24 \text{ N} \\ |F_{T2y}| &= |\vec{T}_1| + |\vec{W}| + |\vec{T}_2'| = \\ &= (15 + 15 + 18) \text{ N} = 48 \text{ N} \end{aligned}$$

$$\begin{aligned} \text{άρα } \vec{F}_{T2} &= \vec{F}_{T2x} + \vec{F}_{T2y} \Rightarrow |\vec{F}_{T2}| = \sqrt{F_{T2x}^2 + F_{T2y}^2} \\ &= \sqrt{24^2 + 48^2} \text{ N} = \sqrt{24^2 + 4 \cdot 24^2} \text{ N} \Rightarrow \\ &\Rightarrow |\vec{F}_{T2}| = \sqrt{5 \cdot 24^2} \text{ N} = \underline{\underline{24\sqrt{5} \text{ N}}} \end{aligned}$$

Α2 $h = 1,8 \text{ m}$ $l = \frac{3\pi}{5} \text{ m}$ $D = k$

Σ_3, Σ_2 + ε.κ. στο σφ M.

αρχικά Σ_3  $\sum \vec{F} = \vec{0} \Rightarrow |\vec{T}_{33}| = |\vec{T}_3| \Rightarrow$
 $\Rightarrow k \cdot d = T_3$

Σ_2 ΑΔΕ (ΑΔΜΕ) ... $\frac{1}{2} m g h = \frac{1}{2} m v_2^2 \Rightarrow$

$$\Rightarrow |\vec{v}_2| = \sqrt{g h} = \sqrt{20 \cdot 1,8} \frac{\text{m}}{\text{s}} = 6 \frac{\text{m}}{\text{s}}$$

$$|\vec{v}_2| = \frac{l}{\Delta t} \Rightarrow \Delta t = \frac{l}{|\vec{v}_2|} = \frac{\frac{3\pi}{5}}{6} \text{ s} = \frac{3\pi}{30} \text{ s} = 0,1\pi \text{ s}$$

οπότε στο Σ_3 έχουμε στην μ.ε Α=α

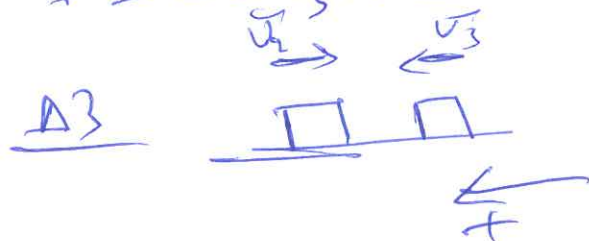
και $T = 2\pi \sqrt{\frac{m_3}{k}}$

οπότε $\Delta t = \frac{T}{4} \Rightarrow T = 4\Delta t = 0,4\pi \text{ s}$

(8)

$$\omega = \frac{2\pi}{T} = \frac{2\pi}{0,4\pi} \frac{r}{s} = 5 \frac{r}{s}$$

$$D = k = m_3 \omega^2 = 125 \frac{N}{m}$$



$$v_3 = v_4 = \omega A = 5 \cdot 0,2 \frac{m}{s} = 1 \frac{m}{s}$$

$$v_2 = -6 \frac{m}{s} \quad (\text{to the left})$$

$$k.e.c. \quad m_2 = m_3 = 5 \text{ kg}$$

amplitude 1266 mm maximum

$$v_3' = v_2 = -6 \frac{m}{s} \quad \text{and} \quad v_2' = v_3 = 1 \frac{m}{s}$$

$$\text{so } m_3 \text{ moves with } v_3' \text{ and } |v_3'| = \omega \cdot A' \Rightarrow$$

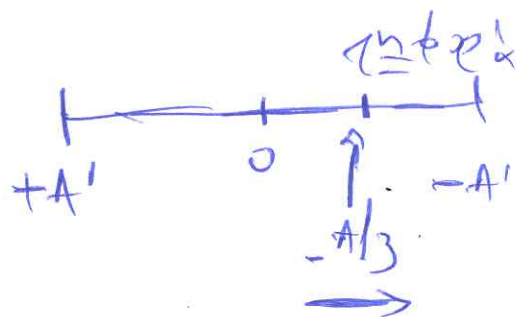
$$\Rightarrow A' = \frac{6}{5} \text{ m} = 1,2 \text{ m}$$

$$\left. \begin{array}{l} x(0) = 0 \text{ m} \\ v(0) < 0 \end{array} \right\} \Rightarrow \left. \begin{array}{l} \psi(0) = 0 \\ \sin \psi(0) < 0 \end{array} \right\} \Rightarrow \left. \begin{array}{l} \phi \in [0, 2\pi) \\ \phi_0 = \pi \end{array} \right\}$$

$$x(t) = 1,2 \sin(5t + \pi)$$

$$\Delta 4 \left\{ \begin{array}{l} k_3 = 8V_3 \\ k_3 + V_3 = V_{max} \end{array} \right\} \Rightarrow 9V_3 = V_{max} \Rightarrow 9 \frac{1}{2} \rho x_3^2 = \frac{1}{2} \rho A^2 \Rightarrow$$

$$\Rightarrow |x_3| = \frac{A'}{3} = 0,4 \text{ m}$$



ADET

$$\frac{1}{2} m_3 v_3''^2 = 8 \frac{1}{2} k \cdot \left(\frac{A'}{3} \right)^2 \Rightarrow$$