

ΘΕΜΑ Α

A1. γ

A2. β

A3. γ

A4. β

A5. α) Σ, β) Σ, γ) Λ, δ) Λ, ε) Σ

ΘΕΜΑ Β

B1.

$$E_{T1} = \frac{1}{2} D_1 A_1^2 = \frac{1}{2} k d^2 = \frac{1}{2} m u^2 \quad (1)$$

$$\Delta \text{ΔΟ } \Sigma f_{\varepsilon\xi} = 0 \Rightarrow P_{\alpha\rho\chi} = P_{\tau\epsilon\lambda} \Rightarrow m u = 2 m u_k \Rightarrow u_k = \frac{u}{2}$$

$$\text{ΟΠΟΤΕ } E_{T2} = \frac{1}{2} 2 m u_k^2 = m \frac{u^2}{4} = \frac{1}{2} \frac{1}{2} m u^2 = \frac{1}{2} E_{T1} \Rightarrow E_{T2} = \frac{1}{2} E_{T1} \Rightarrow \frac{1}{2} D_2 A_2^2 = \frac{1}{2} \frac{1}{2} D_1 A_1^2 \Rightarrow$$

$$\Rightarrow 2 k A_2^2 = \frac{1}{2} k A_1^2 \Rightarrow A_2^2 = \frac{1}{4} A_1^2 \Rightarrow A_2 = \frac{1}{2} A_1 \Rightarrow \frac{A_1}{A_2} = 2$$

$$\text{B2. } \bar{f} = \frac{N}{T_s} = \frac{200}{2} \text{ Hz} \Rightarrow \frac{f_1 + f_2}{2} = 100 \Rightarrow \begin{cases} f_1 + f_2 = 200 \text{ Hz} \\ f_d = f_1 - f_2 = \frac{1}{T_d} = 0,5 \end{cases} \Rightarrow 2f_1 = 200,5 \Rightarrow$$

$$f_1 = 100,25 \text{ Hz} \quad \text{και} \quad f_2 = 99,75 \text{ Hz}.$$

$$\text{B3. } u'_1 = \frac{m_1 - m_2}{m_1 + m_2} u_1 \quad (\text{πρέπει } m_1 < m_2 \text{ για να κινηθεί αριστερά})$$

$$u'_2 = \frac{2m_1}{m_1 + m_2} u_1 \quad \text{ελαστική κρούση με τοίχο της } m_2$$

$$\text{ΑΔΕ } \frac{1}{2} m_1 u_1^2 = \frac{1}{2} m_2 u_2'^2 \Rightarrow \left| \frac{u_1}{u_2'} \right| = \sqrt{\frac{m_2}{m_1}} = \sqrt{\frac{1}{3}} = \frac{1}{\sqrt{3}}$$

για να διατηρηθεί η απόσταση του ζεύγους τα ηχοπρότυπα της ον' με το αμπίχς κ' κεί:

$$\left| \frac{u_1}{u_2'} \right| = \left| \frac{u_1}{u_2} \right| \Rightarrow \frac{|m_1 - m_2|}{m_1 + m_2} = \frac{1}{3} \Rightarrow \frac{m_1 - m_1}{1 + m_1} = \frac{1}{3} \Rightarrow m_1 - m_1 = 2m_2 \Rightarrow m_1 = 3m_2 \Rightarrow \frac{m_1}{m_2} = 3$$

ΘΕΜΑ Γ

$$T = f \left(4 - \frac{1}{2} \right) \Rightarrow 3\pi = 1,2s \Rightarrow f = 0,4\pi$$

$$\lambda_f = \frac{v}{f} = \frac{5}{0,4\pi} = 1,25\pi$$

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$$t_{1,2} = \frac{m}{\lambda} r_{1,2} = \frac{1}{1,25\pi} r_{1,2} = \frac{1}{1,25\pi} r_{1,2}$$

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$$= 10^{-2} \eta \mu (5\pi t - 4\pi + \pi) = 10^{-2} \eta \mu (5\pi t - 3\pi)$$

Γ3. $t_{11} > 1,4s$ έχει ξεκινήσει η συμβολή.

$$\text{ΑΔΕΠ } K + U = U_{\max} \Rightarrow \frac{1}{2} m u^2 + \frac{1}{2} D y^2 = \frac{1}{2} D A'^2 \Rightarrow m u^2 = m w^2 A'^2 - m w^2 y^2 \Rightarrow$$

$$\Rightarrow |\vec{u}| = w \sqrt{A'^2 - y^2} = 5\pi \sqrt{(10^2)^2 - (5\sqrt{3} \cdot 10^{-3})^2} = 5\pi \sqrt{10^{-4} - 75 \cdot 10^{-6}} = 25\pi \cdot 10^{-3} \text{ m/s}$$

$$\Gamma 4. f' = \frac{10}{9} f$$

$$u_\delta = \lambda f = \lambda' f' \Rightarrow \lambda f = \lambda' \frac{10}{9} f \Rightarrow \lambda' = \frac{9}{10} \lambda = 1,8$$

$$|A'_\Sigma| = 2A \left| \sin \frac{\pi}{\lambda} (r_1 - r_2) \right| = 10^{-2} \left| \sin \left(\frac{\pi}{1,8} \cdot 6 \right) \right| = 10^{-2} \sin \frac{60\pi}{18} = 10^{-2} \left| \sin \frac{10\pi}{3} \right| =$$

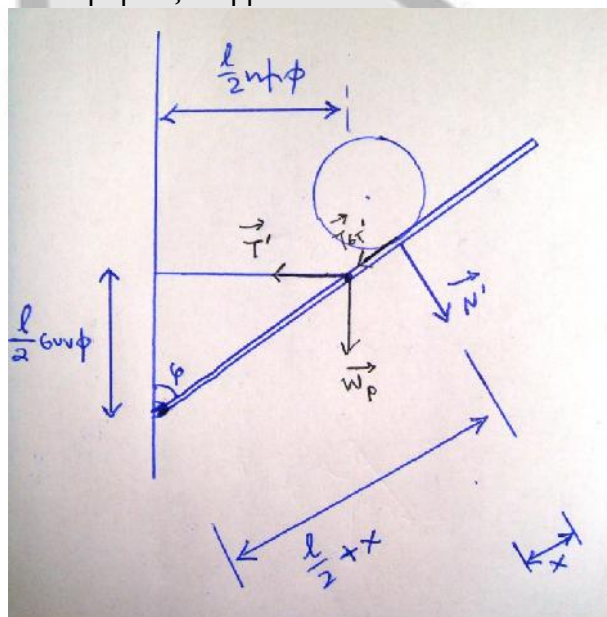
$$= 10^{-2} \left| \sin \left(2\pi + \pi + \frac{\pi}{3} \right) \right| = 10^{-2} \left| -\sin \frac{\pi}{3} \right| = 10^{-2} \frac{1}{2} = 5 \cdot 10^{-3} \text{ m}$$

$$\text{Συνεπώς } \frac{K_1}{K_2} = \frac{u_{\max 1}}{u_{\max 2}} = \frac{\frac{1}{2} D_1 (A'_\Sigma)^2_{\text{παλιό}}}{\frac{1}{2} D_2 (A'_\Sigma)^2_{\text{νέο}}} = \frac{m \cdot w^2 (2A)^2}{m w'^2 (A'_\Sigma)^2} = \frac{4\pi^2 f^2 (10^{-2})^2}{4\pi^2 f'^2 (5 \cdot 10^{-3})^2} = \frac{f^2}{\frac{100}{81} f^2} \cdot \frac{10^{-4}}{25 \cdot 10^{-6}} =$$

$$= \frac{81}{100} \cdot \frac{10^2}{25} = \frac{81}{25}$$

ΘΕΜΑ Δ

Δ1. Η ράβδος ισορροπεί



$$\Sigma \vec{F} = \vec{0} \Rightarrow \begin{cases} \Sigma F_{xc} = 0 \\ \Sigma F_y = 0 \end{cases} \Rightarrow \begin{cases} f_{Ax} = T \\ f_{Ay} = w = 56 \text{ N} \end{cases}$$

$$\Sigma \tau = 0 \Rightarrow \tau_{F(A)} + \tau_{T(A)} + \tau_{w(A)} = 0 \Rightarrow$$

$$\Rightarrow T \frac{l}{2} \sin \varphi - w \frac{l}{2} \eta \mu \varphi = 0 \Rightarrow T = \frac{w \eta \mu \varphi}{\sin \varphi} \Rightarrow$$

$$\Rightarrow T = \frac{56 \cdot 0,6}{0,8} \Rightarrow T = 42 \text{ N} = F_{Ax}$$

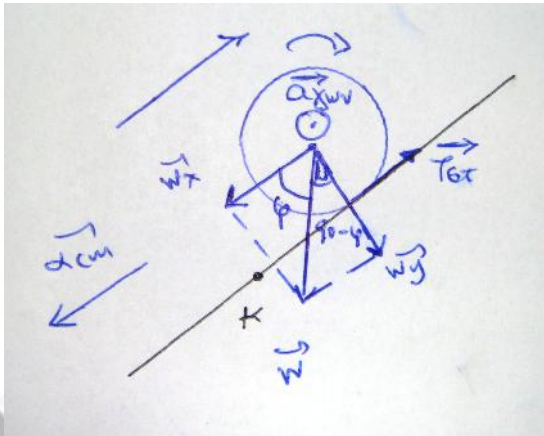
$$\acute{\alpha}\rho\alpha F_A = F_{Ax} + F_{Ay} \Rightarrow |F_A| = \sqrt{F_{Ax}^2 + F_{Ay}^2} =$$

$$= \sqrt{42^2 + 56^2} = \sqrt{(3 \cdot 14)^2 + (4 \cdot 14)^2} =$$

$$= \sqrt{25 \cdot 14^2} = 70 \text{ N}$$

$$\mu\epsilon \ \varepsilon\varphi\theta = \frac{|F_{Ay}|}{|F_{Ax}|} = \frac{56}{42} = \frac{4}{3}$$

Δ2.



$$\Sigma F_x = m a_{cm} \Rightarrow m g \eta \mu \phi - T_{\sigma\tau} = m a_{cm} \quad (1)$$

$$\Sigma \tau_o = I_o \cdot \alpha_{\omega v} \Rightarrow T_{\sigma\tau} \cdot r = \frac{2}{5} m r^2 |\alpha_{\omega v}| \Rightarrow$$

$$\Rightarrow T_{\sigma\tau} = \frac{2}{5} m a_{cm} \quad (2)$$

$$\text{Από (1), (2)} \Rightarrow m g \eta \mu \phi - \frac{2}{5} m a_{cm} = m a_{cm}$$

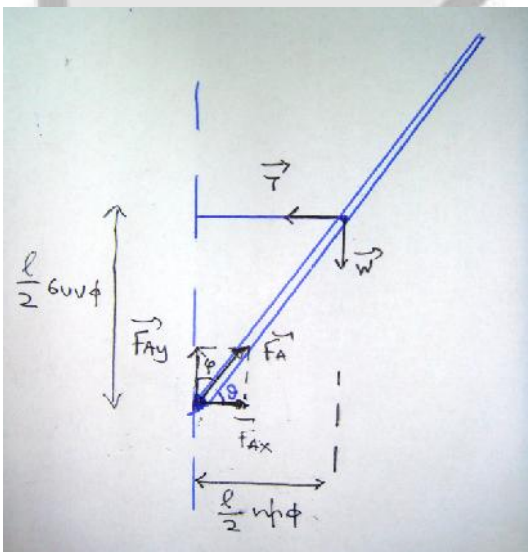
$$\Rightarrow g \eta \mu \phi = \frac{7}{5} a_{cm} \Rightarrow a_{cm} = \frac{5}{7} g \eta \mu \phi \Rightarrow$$

$$\Rightarrow a_{cm} = \frac{50}{7} \cdot \frac{6}{10} = \frac{30}{7} \text{ m/s}^2$$

$$\text{και } |\alpha_{\omega v}| = \frac{a_{cm}}{r} = \frac{\frac{30}{7}}{\frac{1}{70}} = \frac{70 \cdot 30}{7} \Rightarrow |\alpha_{\omega v}| = 300 \text{ rad/s}^2$$

οπότε $\alpha_{\omega v}$ $\left\{ \begin{array}{l} \text{μέτρο } 300 \frac{\text{rad}}{\text{s}^2} \\ \text{διεύθ. τον αξ. περιστροφής που διέρχεται από το } O \text{ κάθετο στο επ. της περισ. του κίνησης} \\ \text{φορά απ' τη σελίδα προς τον αναγνώστη.} \end{array} \right.$

Δ3.



$$0 \leq x \leq \frac{\ell}{2} = 1 \text{ m}$$

σε τ.θ. του σώματος η ράβδος ισορροπεί.

$$\Sigma \tau_A = 0 \Rightarrow T' \frac{\ell}{2} \sin \phi - N' \left(\frac{\ell}{2} - x \right) - M g \frac{\ell}{2} \eta \mu \phi = 0$$

$$\Rightarrow T' \frac{\ell}{2} \sin \phi = N' \left(\frac{\ell}{2} - x \right) + M g \frac{\ell}{2} \eta \mu \phi \Rightarrow$$

$$\Rightarrow T' = 45 + 3x$$

Δ4.

